

Methods of measuring Cell Elasticity

A comprehensive overview

Courtesy of Katja Taute

Motivation

- General attempt to apply laws of physics (derived for inanimate matter) to living objects!!
- We learn something about amazing material properties of cells
- Mechanical properties of cells reveal architecture of the cytoskeleton
- How are cell function and mechanical properties correlated?
- Changes in cell elasticity often monitor physiological status of cell, e.g. cancer cells are less elastic than healthy cells.

Basics: What is Elasticity?

In the easiest case (homogeneous isotropic solid):

Compression/Stretching

Hooke's law: $F \sim \Delta x$

Stress: $\sigma = F/A$

Strain: $\epsilon = \Delta x/x$

$$\sigma = E\epsilon$$

E: Elasticity or Young's Modulus

Shear

$F_T \sim \Delta x_T$

Shear stress: $\sigma_s = F_T/A$
Shear strain: $\epsilon_s = \Delta x_T/x$

$$\sigma_s = G\epsilon_s$$

$G = E/(2+2\mu)$,
 μ : Poisson number
G: Shear modulus

Does this apply to cells?

- **Cells are neither homogeneous nor isotropic**
 - Cells have internal structure
 - Cell components have different characteristics
- **Cells are not solid**
 - Cell material rather resembles a polymeric liquid or gel
- **Cells also show viscous behaviour**
 - Mechanical energy can be dissipated into heat
- **Cells are alive**
 - Cell can respond to external forces e.g. by strengthening the cytoskeleton

→ Some difficulties extracting E for a cell

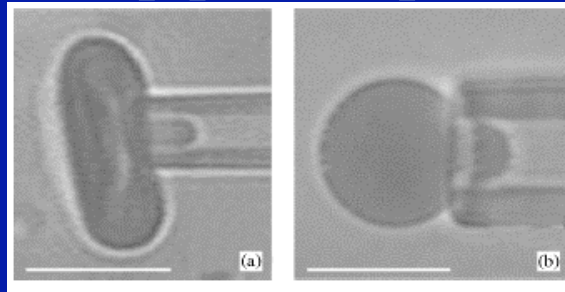
How to deal with the difficulties

- **Inhomogeneity**
 - Use local measurements or averages over whole cell
- **E not practicable**
 - Define other characteristic parameter
- **Viscosity**
 - Choose appropriate timescales to avoid viscous contribution
 - Incorporate viscosity into the model
 - Use complex elasticity modulus $E^*(\omega)$ or shear modulus $G^*(\omega)$
 - Storage modulus $G'(\omega) = \text{Re}(G^*)$ accounts for elasticity
 - Loss modulus $G''(\omega) = \text{Im}(G^*)$ accounts for viscosity
 - Be aware that these quantities are frequency-dependent
- **Living subject of study**
 - Allows for the study of biological response!

Techniques

- **Basic mechanical methods**
 - Micropipette Aspiration
 - Cell Poking
 - Silicon Micromachines
 - Atomic Force Microscopy
 - Biointerface Probe
 - Tensile Tester
 - Microplates
- **Magnetic methods**
 - Magnetic Twisting
 - Attached Magnetic Beads
 - Embedded Magnetic Beads
- **Optical methods**
 - Optical Tweezers
 - Optical Stretcher
- **Other**
 - Acoustic Microscopy
 - Laser Tracking
 - Microrheology
 - Hydrodynamic Flow

Micropipette Aspiration



Principle

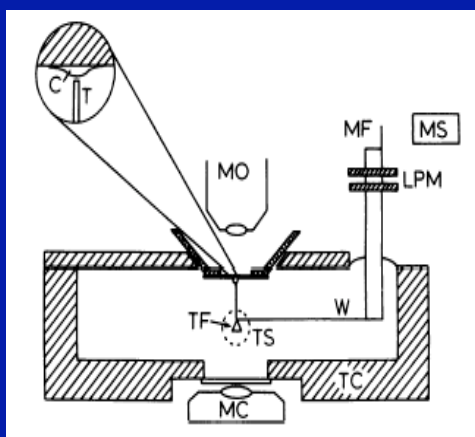
- suction pressure is created in micropipette
- leading edge of aspirated cell is tracked

Details

- tracking accuracy: $\pm 25\text{nm}$
- suction pressure range: $0.1\text{-}1000\text{Pa}$
- force range $10\text{pN}\text{-}10\text{mN}$
- pressure vs edge position yields E

Hochmuth (2000) *J. Biomech.* 33:15-22

Cell Poker (1)



Principle:

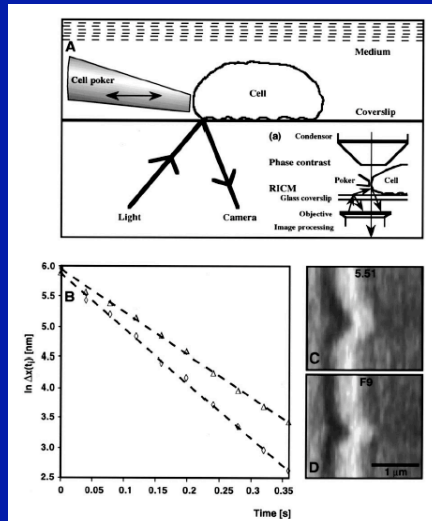
- tip mounted on flexible wire
- position of both tip and wire arm are measured to determine deflection

Details

- tip: glass stylus $d=2\mu\text{m}$
- position precision: $0.1\mu\text{m}$
- $k_{\text{wire}}=38\text{pN/nm}$
- force resolution $\sim 4\text{nN}$
- force range: $<30\text{nN}$

Petersen et al. (1982) *Proc. Natl. Acad. Sci.* 79:5327-5331

Cell Poker (2)



Goldmann et al. (1998) FEBS Lett. 424:139-142

Principle

- indentation by poker
- immediate retraction
- monitor cell relaxation by reflection interference contrast microscopy (RICM)

Details

- position precision: $\sim 1\text{nm}$
- analysis: $\ln(x(t_i)) \sim -k \cdot t_i$
- k characterizes resistance to indentations

Silicon Micromachines

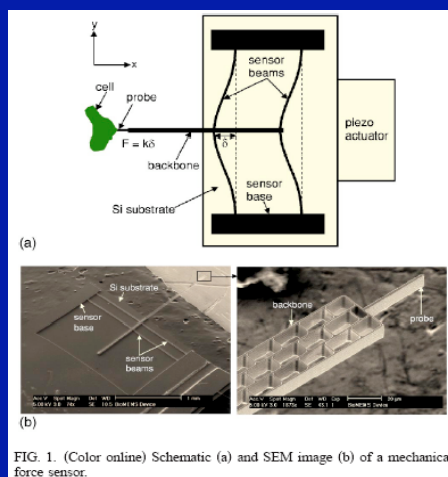


FIG. 1. (Color online) Schematic (a) and SEM image (b) of a mechanical force sensor.

Principle

- silicon poker fixed to beam of known elasticity
- poker and sensor position are monitored
- Also stretching experiments by glueing tip to cell

Details

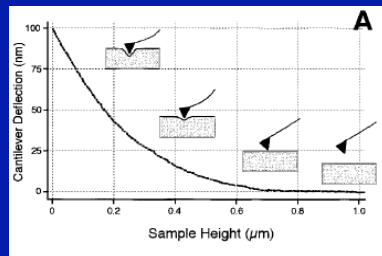
- sensor is grown in SCREAM process
- $k_{\text{beam}} = 3.4\text{nN}/\mu\text{m}$
- position accuracy: $\sim 0.14\mu\text{m}$
- force resolution $\sim 0.5\text{nN}$
- nN and μm range

Yang and Saif (2005) Rev. Sci. Instrum. 76:044301

Atomic Force Microscopy (AFM)

Principle

- Record player principle: cantilever scans sample
- Cantilever deflection is recorded by laser reflection
- Force-distance-maps can be produced for each x-y-position

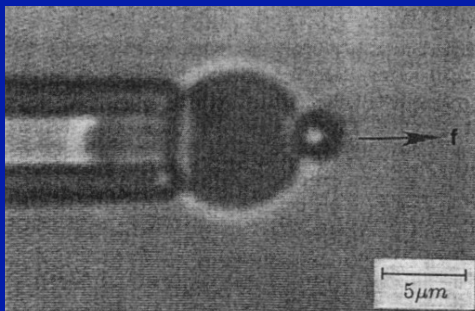


Details

- $k_{\text{cantilever}} \sim 10\text{-}50\text{pN/nm}$
- Deflection of laser beam is recorded with 2-segment photo diode
- Cantilever tip can be modified with beads for more convenient geometry and nondestructive imaging (Mahaffy et al. (2000). Phys. Rev. Lett. 85:880:883)

Al-Hassan et al. (1998) Biophys. J. 74:1564-1578

Biointerface Probe



Principle

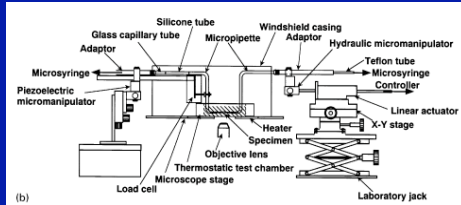
- bead probe glued to red blood cell (RBC) held by micropipette
- RBC acts as variable force transducer

Details

- latex bead $d=2\text{-}3\mu\text{m}$
- probe position precision $\sim 5\text{nm}$
- suction pressure \sim RBC surface tension \sim RBC stiffness
- $k=1\text{fN/nm}\text{-}10\text{pN/nm}$
- force range $10^{-2}\text{-}10^3\text{pN}$

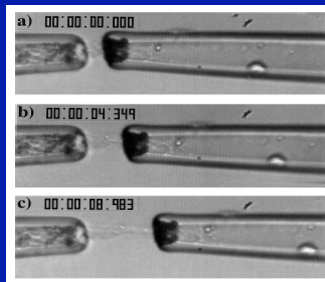
Evans et al. (1995) Biophys. J. 68:2580-2587

Tensile Tester



Principle:

- cell is stretched between two micropipettes
- distance between pipette tips measures elongation

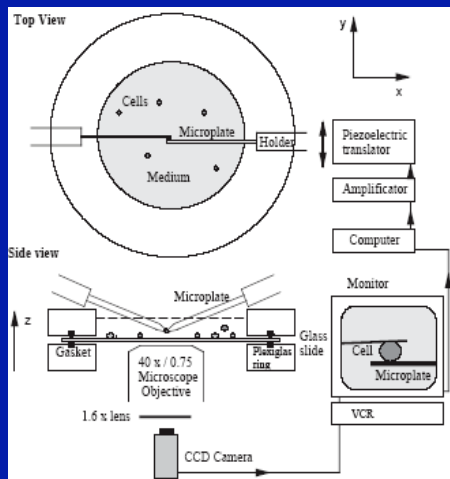


Details

- displacement resolution: $0.24\mu\text{m}$
- forces are measured with semiconductor strain gauge, accuracy $\pm 50\text{nN}$

Miyazaki et al. (2000) J. Biomech. 33:97-104

Microplates



Principle

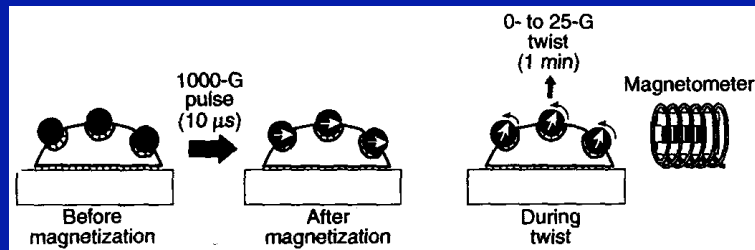
- cell is squeezed/stretched between a solid and a flexible microplate
- cell deformation is observed

Details

- solid microplate is moved with piezo
- force range: $10\text{-}100\text{nN}$
- $k_{\text{microplate}} = 1\text{-}10\text{nN}/\mu\text{m}$
- position accuracy: $0.4\mu\text{m}$
- Analysis: $\sigma(t) = \epsilon_0(k_0 + k_1 e^{-t\tau})$

Thoumine and Ott. (1997) J. Cell Sci. 110:2109-2116

Magnetic Twisting



Principle

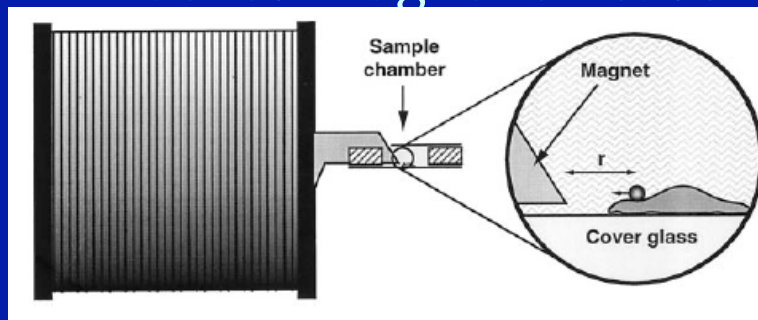
- surface-bound ferromagnetic beads are magnetized by strong field pulse
- then twisted by small perpendicular field
- twisting angle reflects shear response

Details

- field pulse: 0.1T for $10\mu\text{s}$
- twisting field: $<25 \cdot 10^{-5}\text{T}$
- twisting angle is inferred from magnetometer measurements

Wang et al. (1993) Science 260:1124-1127

Attached Magnetic Beads



Principle

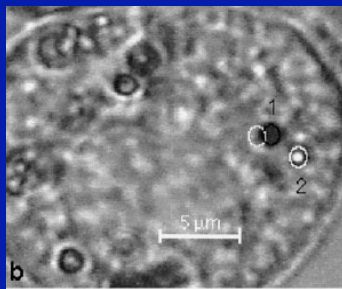
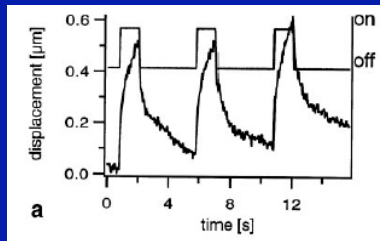
- force pulses are applied to paramagnetic beads bound to cell surface
- creep response and relaxation are recorded

Details

- bead $d=4.5\mu\text{m}$ bound to integrin receptors
- force range: up to 10nN
- position accuracy: $\sim 10\text{nm}$
- time resolution: 0.04s

Bausch et al. (1998) Biophys. J. 75:2038-2049

Embedded Magnetic Beads



Bausch et al. (1999) Biophys. J. 76:573-579

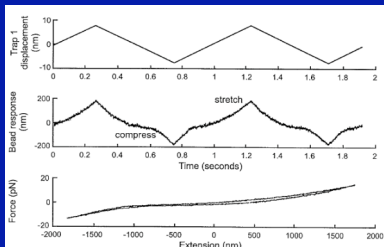
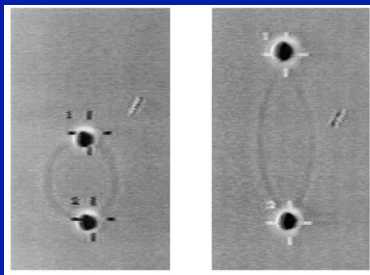
Principle

- field pulses are applied to ferromagnetic beads in cells (macrophages)
- creep response and recovery curves determine viscoelasticity

Details

- bead size: $d=1.3\mu\text{m}$
- force range: 300-700pN
- time resolution: 0.04s

Optical Tweezers



Sleep et al. (1999) Biophys. J. 77:3085-3095

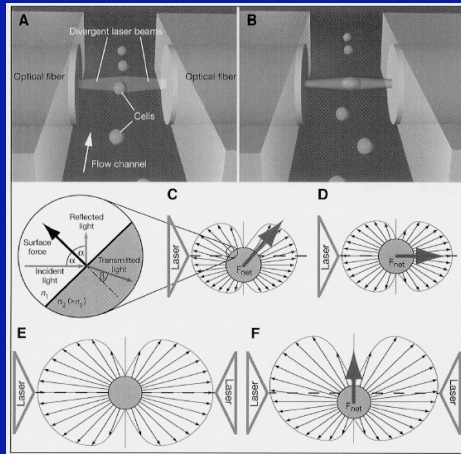
Principle

- beads glued to cell are held in optical traps
- one is moved and the response of the second is measured

Details

- $k_{\text{trap}}=0.08\text{pN/nm}$
- forces $< 25\text{pN}$
- bead $d=1\mu\text{m}$
- bead 1 is moved using acousto-optical modulator
- bead 2 response is monitored with quadrant detector

Optical Stretcher



Principle

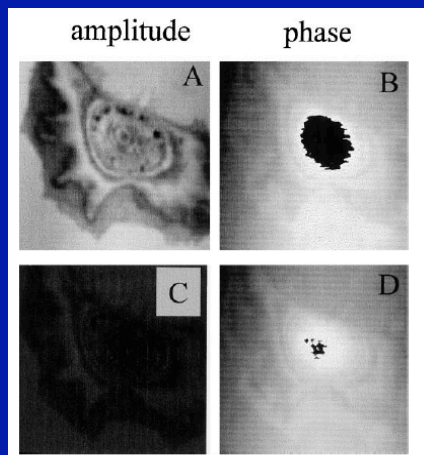
- No absorption → laser beam passes through cell
- Momentum conservation → surface stress
- Cell deformation is measured in terms of aspect ratios
- No physical contact required!

Details

- surface force scales with n_{cell} and laser intensity
- force range: $\sim 10^2 \text{pN}$

Guck et al. (2005) Biophys J. 88:3689-3698

Acoustic Microscopy



Principle

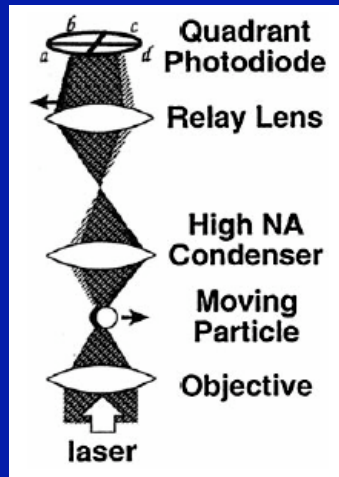
- acoustic lens scans sample
- phase and amplitude of reflected wave encode sound velocity and attenuation
- sound velocity is a measure of elasticity

Details

- VHF ultrasound: $\sim 1 \text{GHz}$
- scan: 512×256 pixels
- spatial resolution: $3 \mu\text{m}^2$

Kundu et al. (2000) Biophys. J. 78:2270-2279

Laser Tracking Microrheology (LTM)



Principle

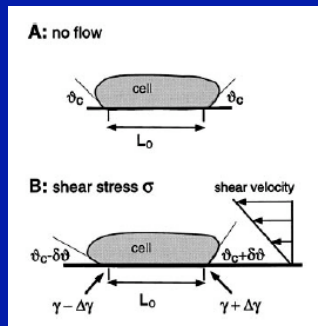
- some cells contain granules (lipid droplets), $d \approx 0.3 \mu\text{m}$
- their Brownian motion in cytoplasm is observed by light scattering
- mean square displacement is measure for viscoelasticity of surrounding medium

Details

- laser: $P=0.13\text{mW}$, $\lambda=670\text{nm}$
- displacement calibration with polystyrene beads (similar optical properties)
- displacement resolution: $<1\text{nm}$
- MSD: $\langle R^2(\tau) \rangle = \langle (r(t+\tau) - r(t))^2 \rangle$

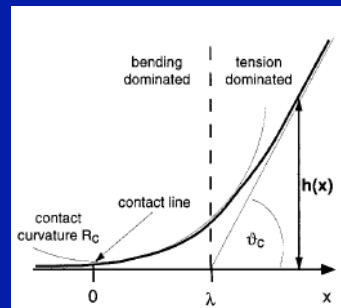
Yamada et al. (2000) Biophys. J. 78:1736-1747

Hydrodynamic Flow



Principle

- Hydrodynamic flow deforms cell
- Cell profile is determined by membrane bending modulus



Details

- Shape is analyzed using reflection interference contrast microscopy (RICM)
- λ yields bending modulus

Simson et al. (1998). Biophys.J. 74:514-522

Brief Review of Techniques

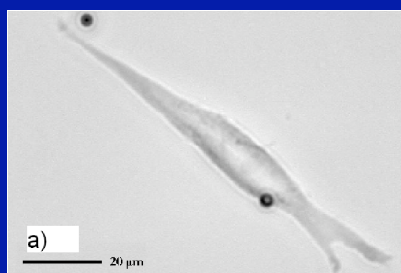
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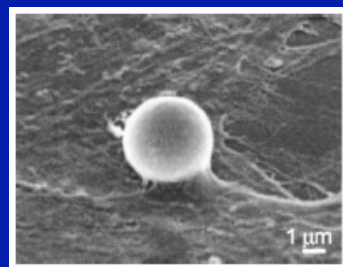
Experimental Results

Techniques for Attached Cells



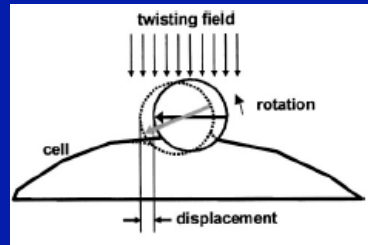
Adherent cells

Beads as handles

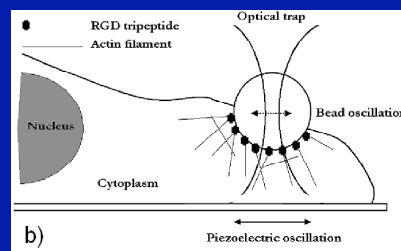


Techniques for Attached Cells

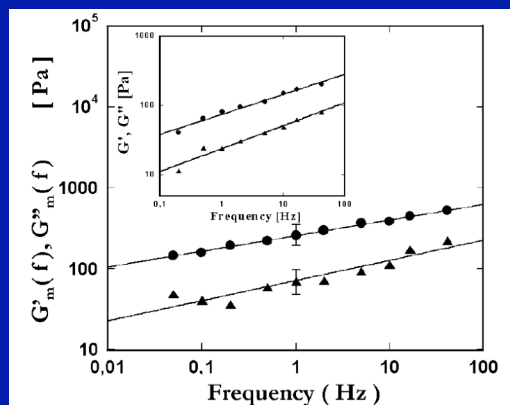
Magnetic bead twisting
(Fabry et al., *PRL* 2001; *PRE* 2003)



Optical Tweezers
(Balland et al., *Eur. Biophys. J.*, 2005)



Rheological Results: Attached Cells

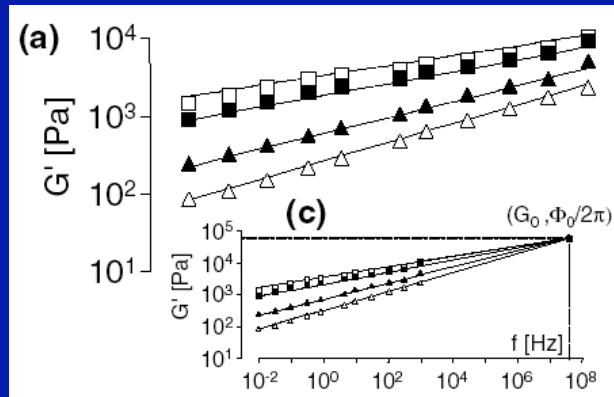


$$G' \propto \omega^x$$

$$\log(G') = x \cdot \log(\omega) + c$$

Balland et al., *Eur. Biophys. J.* (2005)

Rheological Results

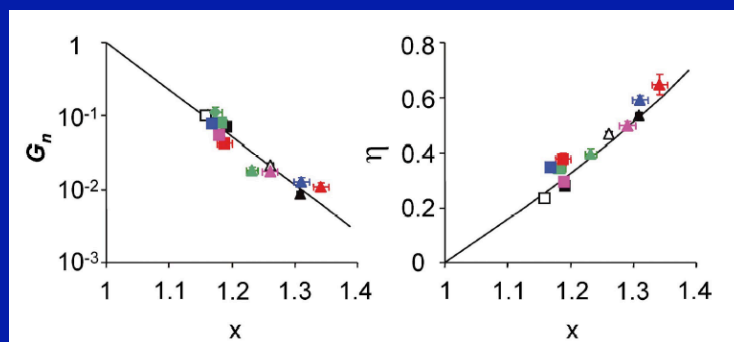


$$\log(G') = x \cdot \log(\omega) + c$$

All experiments with all kinds of different cells can be described by a Master Curve; only difference is x !

Fabry et al., *PRL* 2001; *PRE* 2003

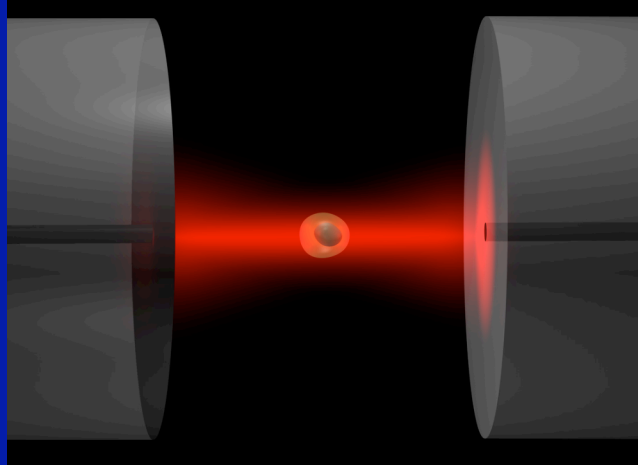
Rheological Results



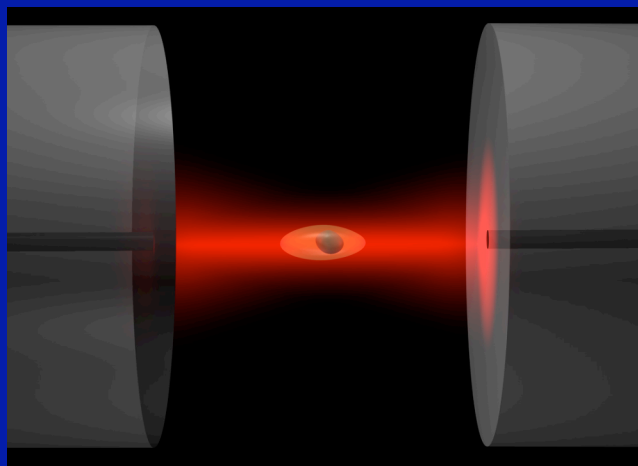
Can be described by theory of “soft glassy materials” (Sollich, 1997, 1998) (Foams, pastes, colloids, slurries, ...)

- very soft (Pa – kPa)
- G' and G'' follow the same power law (no single relaxation time)
- x is an effective noise temperature
- microscopic origin???

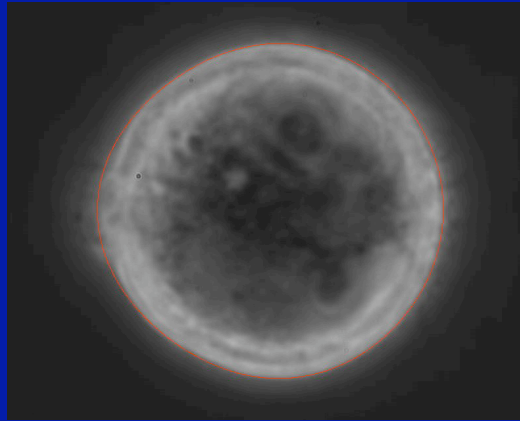
Deforming Cells in Suspension?



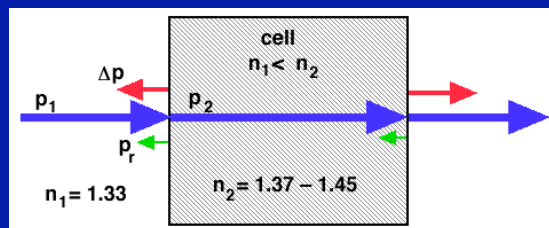
The Optical Stretcher



The Optical Stretcher



Optical Surface Forces



Momentum of a light ray

$$p = \frac{n_i E}{c}$$

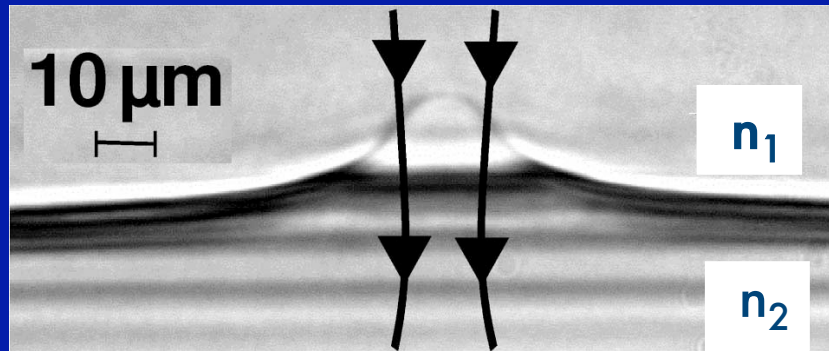
- Whenever light enters or exits a dielectric medium it exerts a force **AWAY** from the denser medium and **NORMAL** to the surface

Conservation of momentum at surface

$$\begin{aligned} \Delta p &= \frac{E}{c} (n_1 + Rn_1 - (1 - R)n_2) \\ &= \frac{2n_1 E}{c} \left(\frac{1 - n}{1 + n} \right) < 0 \\ n &= \frac{n_2}{n_1} > 1 \end{aligned}$$

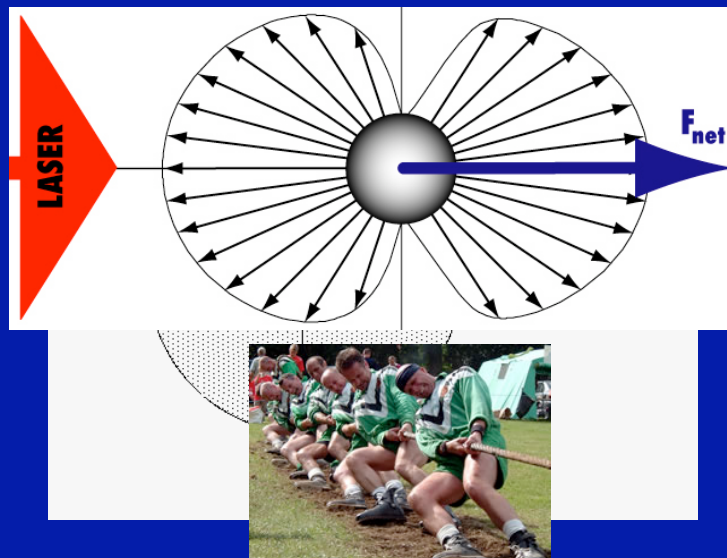
J. Guck, et al. *Phys. Rev. Lett.* **84**:5451, 2000

Surface Deformation

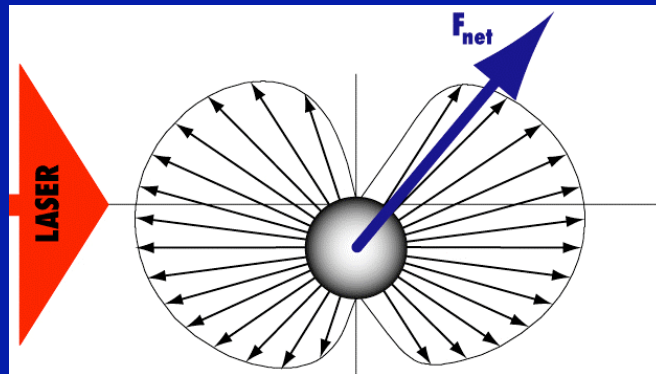


Casner and Deville. *Phys. Rev. Lett.*, 2001

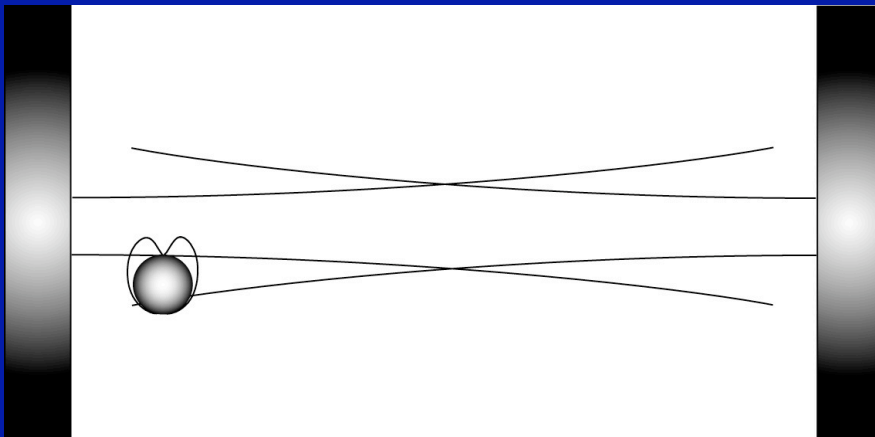
Surface Forces in Gaussian Beams



Surface Forces in Gaussian Beams



Optical Stress in DBLT



Microrheology on Fibroblasts



Step-stress
experiment

Deformation
($\gamma_{\max} = 7.5\%$)

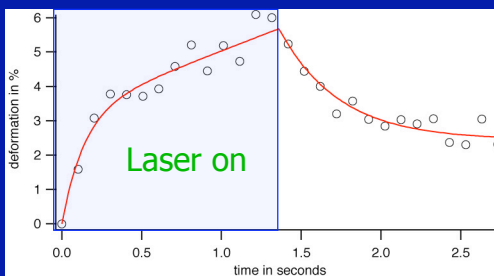
Viscoelastic Characterization

$$\sum_{i=0}^n a_i \partial_t^i \gamma(t) = \sum_{j=0}^m b_j \partial_t^j \sigma(t)$$

$$a_1 \partial_t \gamma(t) + a_2 \partial_t^2 \gamma(t) = \sigma(t) + b_1 \partial_t \sigma(t)$$

$$\gamma_{ext}(t) = F_G \sigma_0 \left(\frac{b_1}{a_1} - \frac{a_2}{a_1^2} \right) \left(1 - e^{-\frac{a_1}{a_2} t} \right) + \frac{F_G \sigma_0}{a_1} t$$

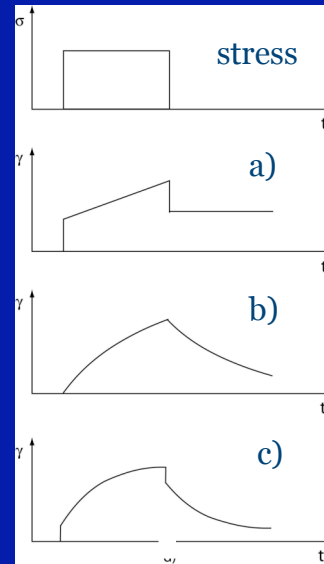
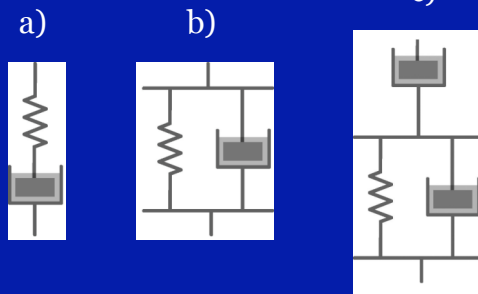
$$\gamma_{rel}(t) = F_G \sigma_0 \left(\frac{b_1}{a_1} - \frac{a_2}{a_1^2} \right) \left(1 - e^{-\frac{a_1}{a_2} t_1} \right) e^{-\frac{a_1}{a_2} (t-t_1)} + \frac{F_G \sigma_0}{a_1} t_1$$



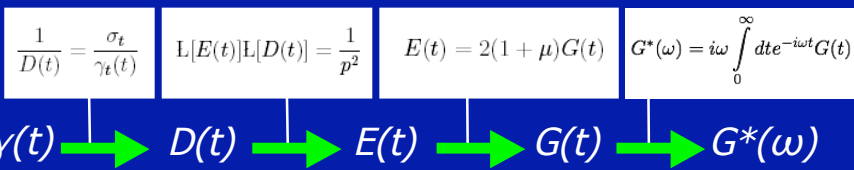
F. Wottawah et al., *Phys. Rev. Lett.* **95** (2005)

Viscoelastic Models

- a) Maxwell element
- b) Voigt element
- c) Voigt element w/ dashpot

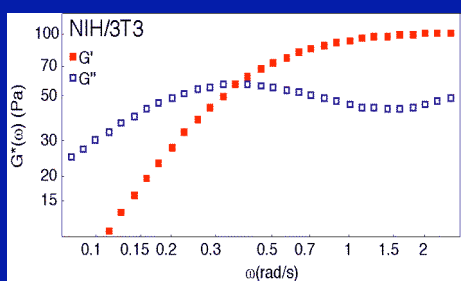


Viscoelastic Characterization



Frequency dependent shear modulus:

$$G^*(\omega) = G'(\omega) + iG''(\omega)$$



F. Wottawah et al., *Acta Biomat.* (2005)

Microscopic Origin

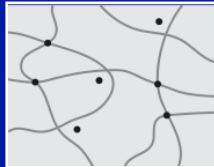
non-crosslinked /
entangled



$$G' \approx 5 \text{ Pa}$$

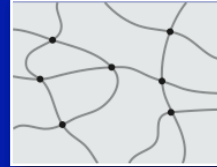
F. C. MacKintosh, et al, Phys. Rev. Lett. 75, 4425 (1995).

transiently
crosslinked



$$G'_{NIH/3T3} = 100 \pm 10 \text{ Pa}$$

fully
crosslinked



$$G' \approx 680 \text{ Pa}$$

D. Morse, Macromol. 31, 7030 (1998), 31, 7044 (1999)

F. Wottawah et al., *Acta Biomat.* (2005)

Microscopic Origin

non-crosslinked /
entangled



Reptation time

$$\tau_r \approx 400 \text{ s}$$

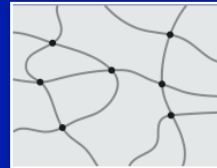
transiently
crosslinked



Relaxation time

$$\tau_t = 2.8 \pm 0.5 \text{ s}$$

fully
crosslinked



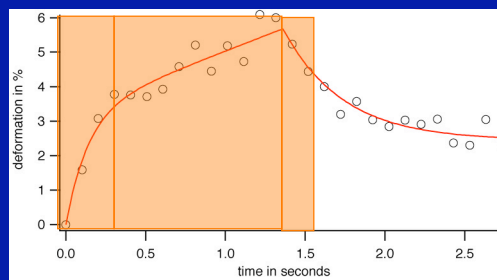
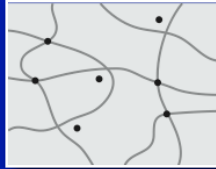
Wachsstock et al., Biophys J. (1994)
Goldmann et al., FEBS Lett. (1998)
Mullins et al. PNAS (1998)

Actin Crosslinker	k (Dissociation Rate Constant)	1/k (secs)
α -actinin	2.7	0.6
Filamin/ABP	0.6	1.667
Arp 2/3	0.5-5	0.2-2

F. Wottawah et al., *Phys. Rev. Lett.* (2005)

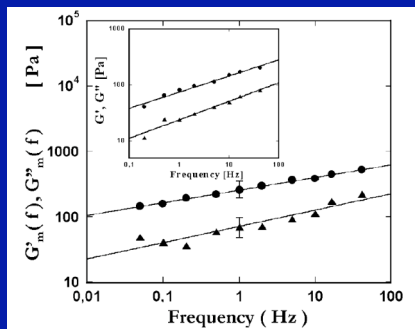
Microscopic Origin

Transiently crosslinked: beyond $1/k_1$ the cell behaves like a fluid

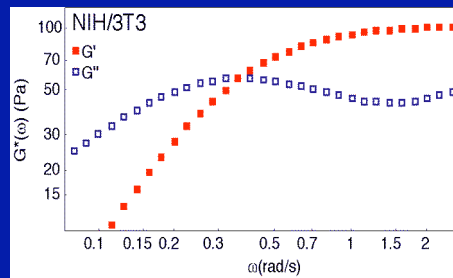


Explanation of the Difference?

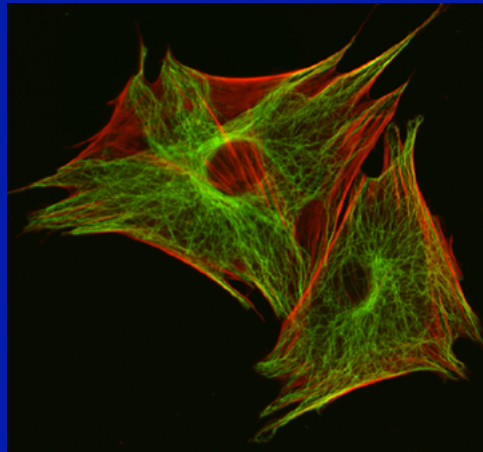
Attached



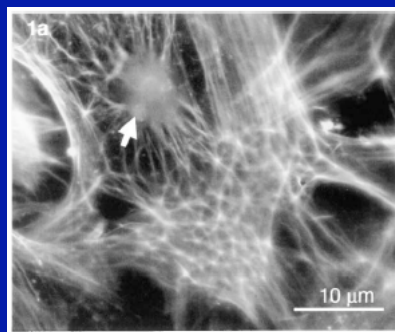
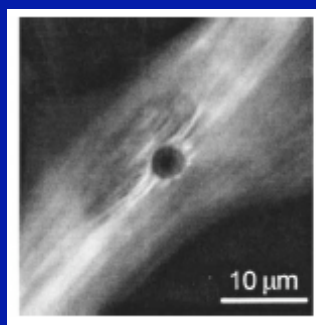
Suspended



Cytoskeleton in Adherent Cells

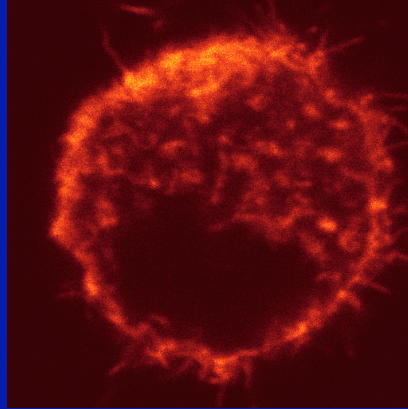


Handles attach to Stress Fibers



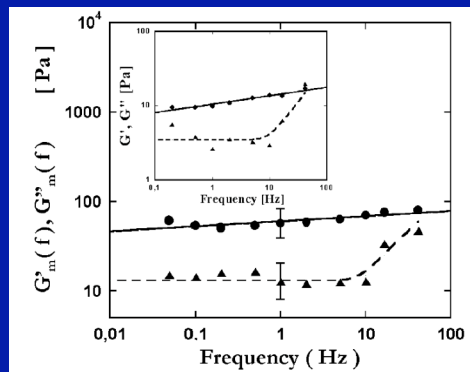
Methods probe dynamics of the contractile actin-myosin stress fibers (very local measurement).
Response on many time-scales!

Cytoskeleton in Suspension



No stress fibers present, only isotropic network.
This allows the application of polymer theories and
microscopic interpretation of results!
Optical Stretcher measures global properties.

The Effect of Blebbistatin



Blebbistatin inhibits the activity of myosin.

--> other relaxation times appear!!

Balland et al., *Eur. Biophys. J.* (2005)

Cell Mechanics as a Cell Marker

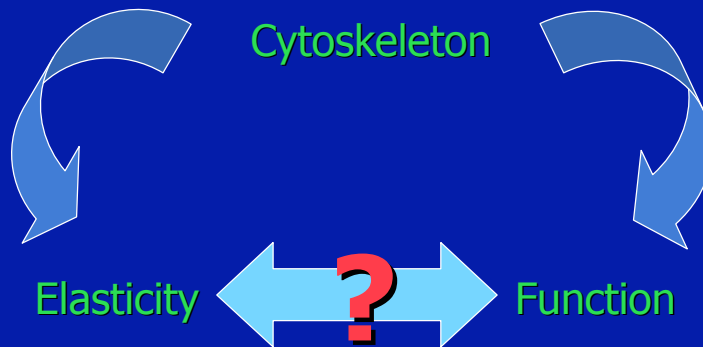
The Cytoskeleton

Far from being static and passive, it is a very dynamic system that fulfills many important cell functions.

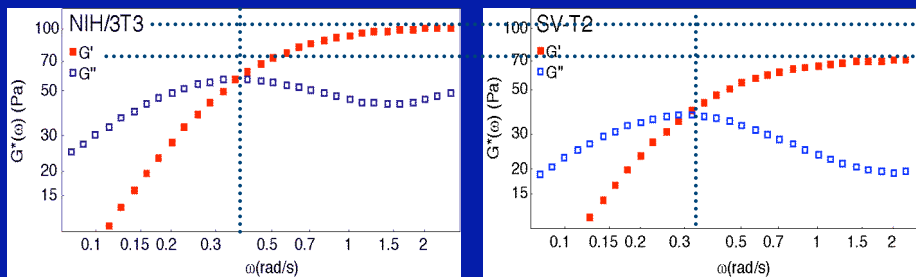


Courtesy of Dr. Stefan Grill, MPI f. MCB Dresden

The Cytoskeleton



Comparison of Different Cell Types

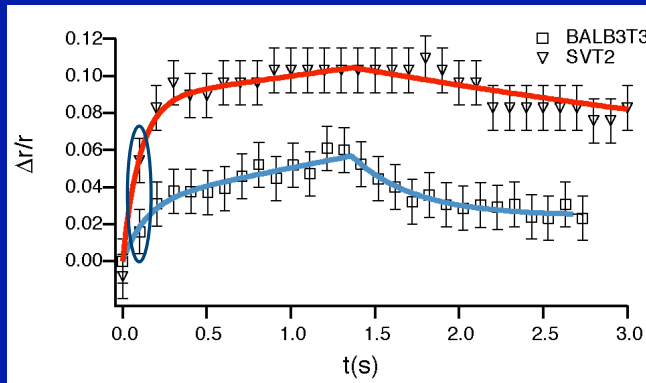


	Normal Cell	Cancer Cell
G [Pa]	100 ± 10	69 ± 5
η [Pa s]	426 ± 97	232 ± 44
τ [s]	2.2 ± 1.1	1.9 ± 0.6

F. Wottawah et al., *Phys. Rev. Lett.* **95** (2005)

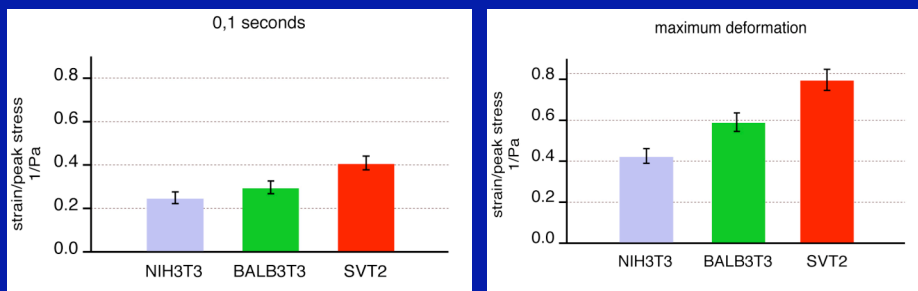
F. Wottawah et al., *Acta Biomat.* (2005)

Deformability of Cells



S. Schinkinger et al., *J. Biomed. Opt.* (submitted)

Optical Deformability

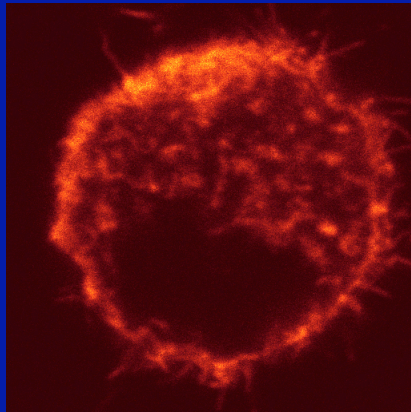


Only 30 cells each measured.
Deformability of cells is a tightly regulated cell marker

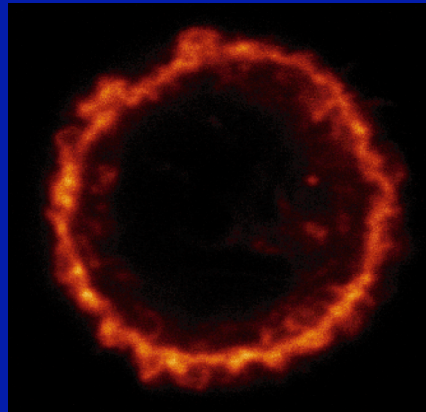
S. Schinkinger et al., *J. Biomed. Opt.* (submitted)

Cytoskeleton in Cancer Cells

Normal fibroblast



Cancerous fibroblast

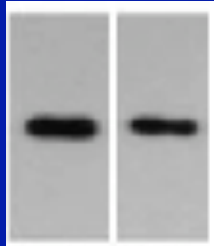


Structure of cytoskeleton in cancer cells is different

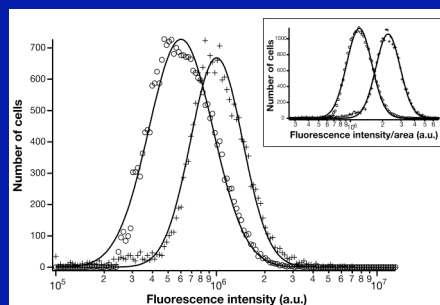
Amount of F-Actin

Western Blot

Normal fibroblast Cancerous fibroblast



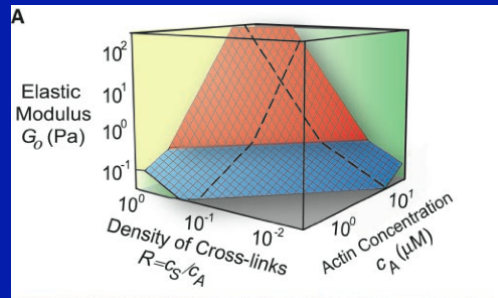
Laser Scanning Cytometry (LSC)



Actin amount is reduced by 30-35%

J. Guck et al., *Biophys. J.* **88**(5) (2005)

Deformability as Cell Marker



M. Gardel et al., *Science* (2004)

$$G' \propto C_A^{2-6.7}$$

Cell deformability provides built-in, strong amplification of molecular changes in single living cells.